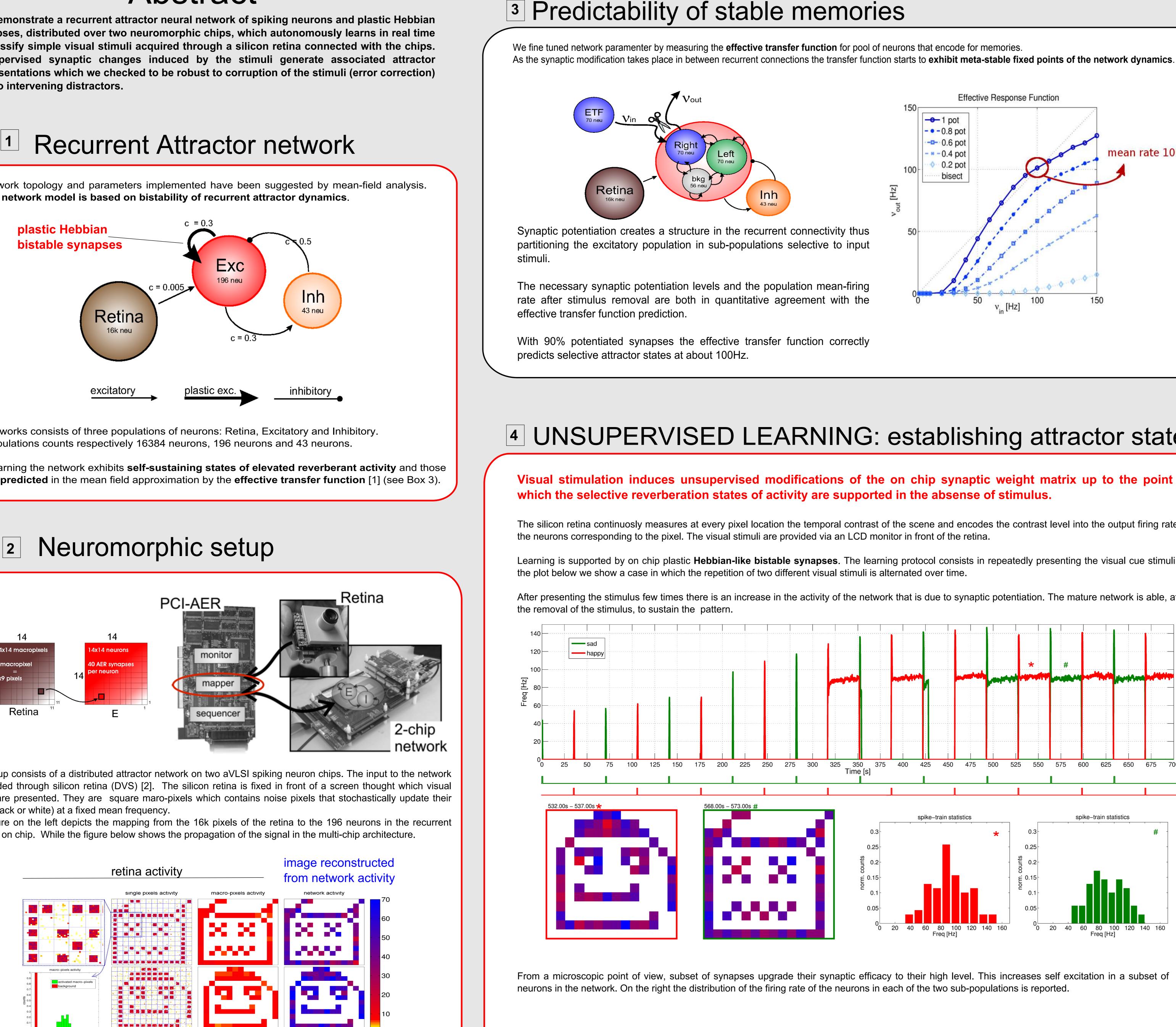
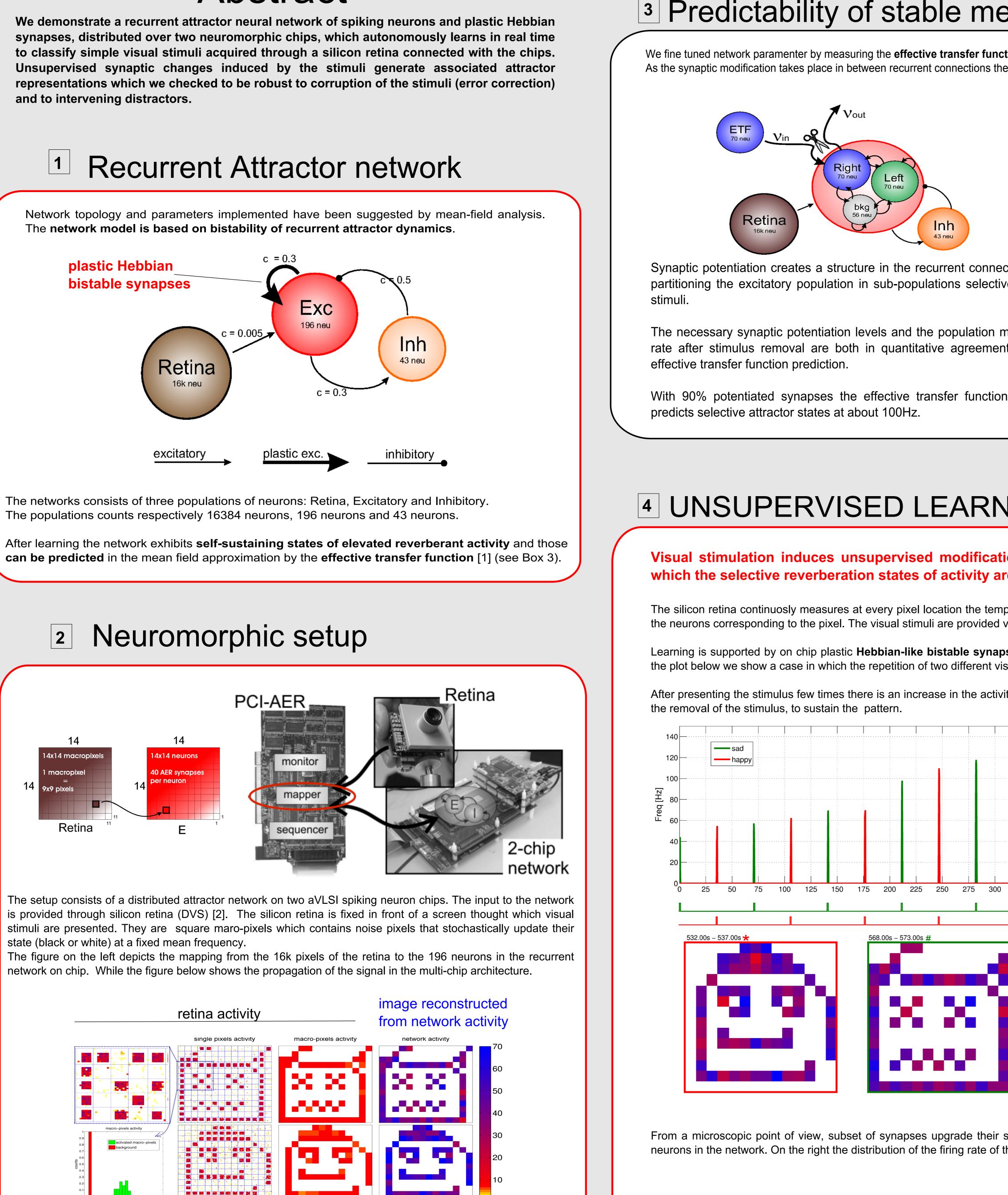
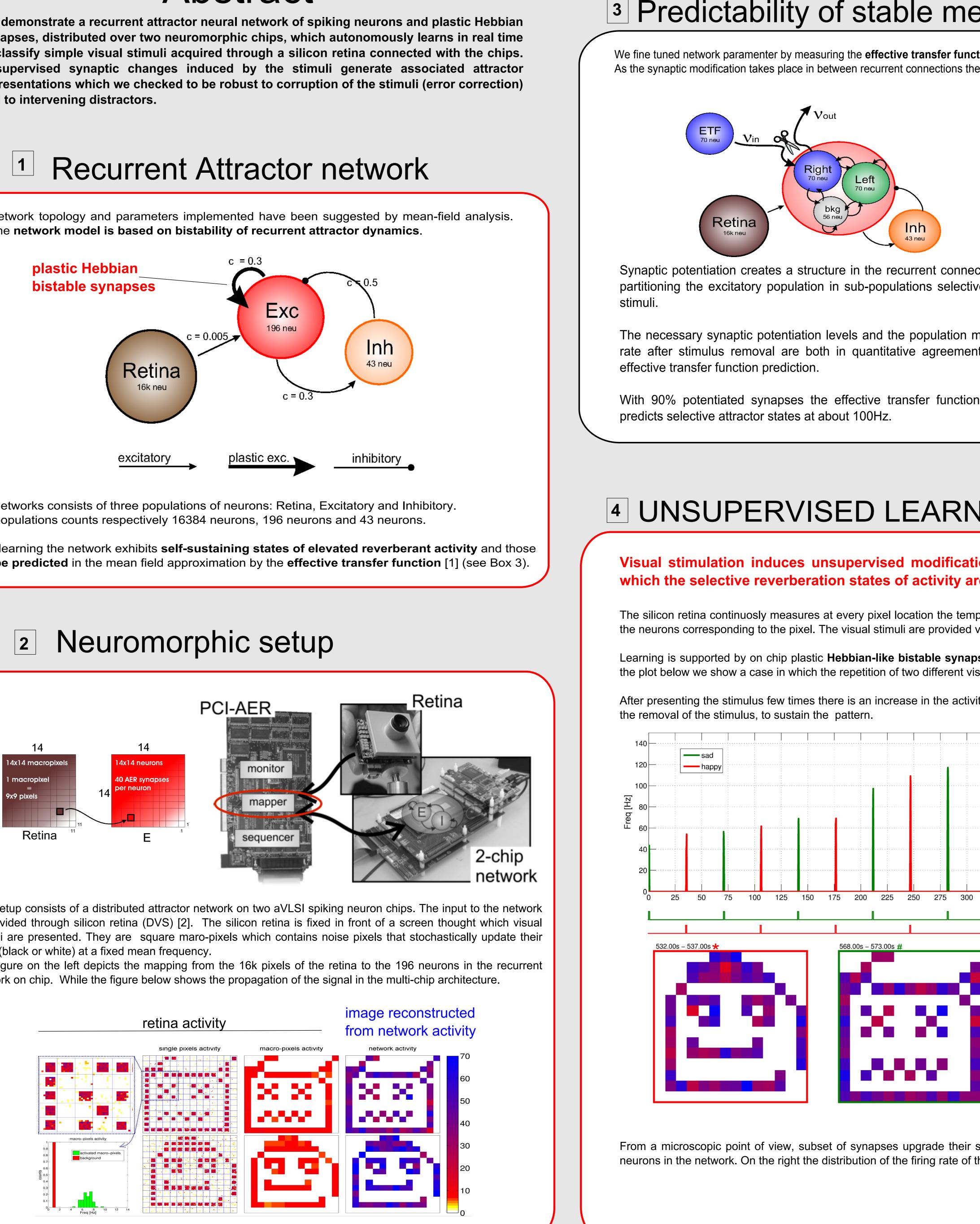
NeuComp2013

Abstract

The network model is based on bistability of recurrent attractor dynamics.

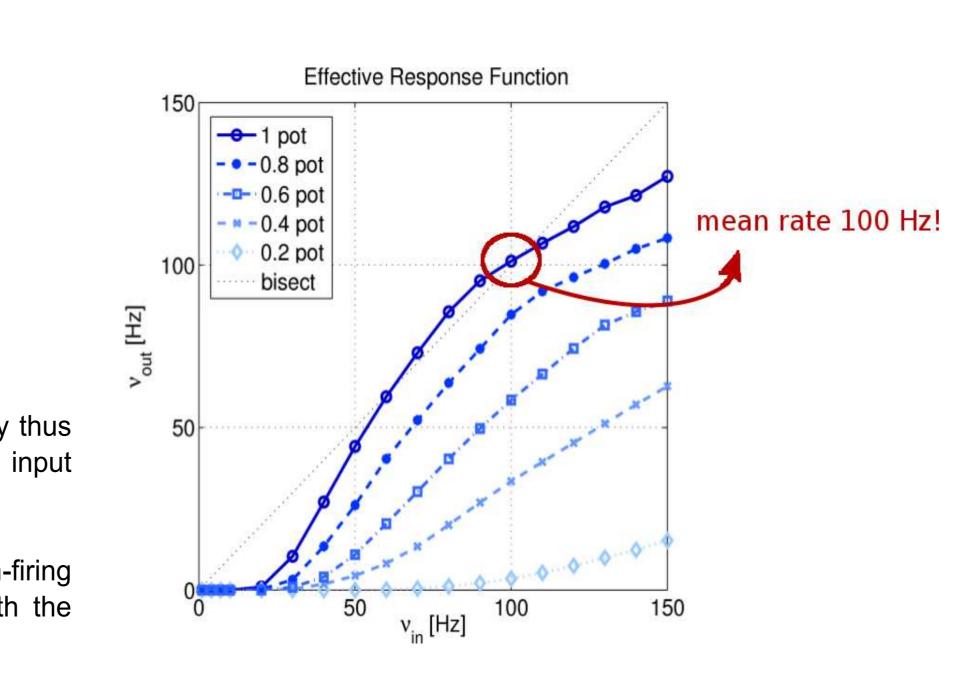






Learning visual stimuli in neuromorphic VLSI Federico Corradi¹, Massimiliano Giulioni², Vittorio Dante² and Paolo Del Giudice^{2,3}

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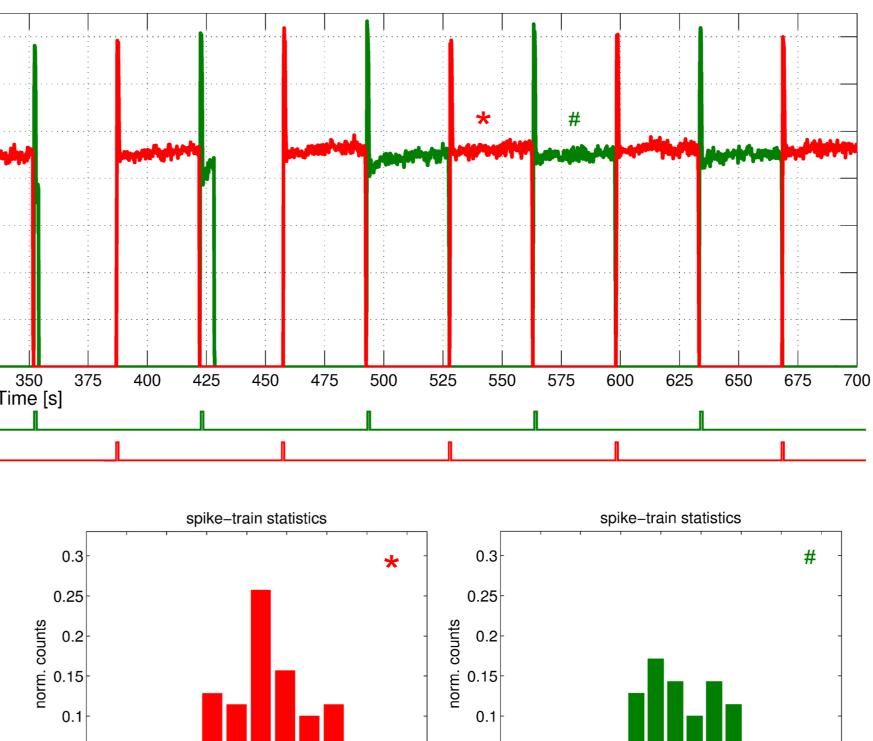
4 UNSUPERVISED LEARNING: establishing attractor states

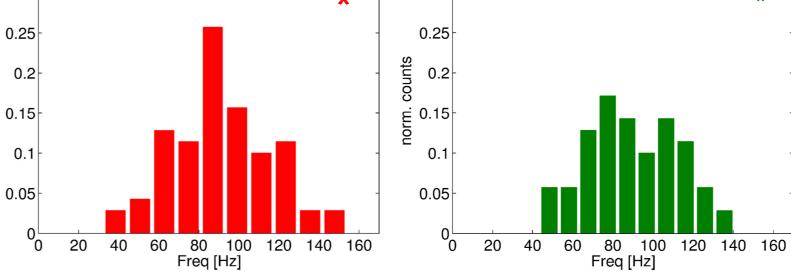
Visual stimulation induces unsupervised modifications of the on chip synaptic weight matrix up to the point in

The silicon retina continuosly measures at every pixel location the temporal contrast of the scene and encodes the contrast level into the output firing rate of

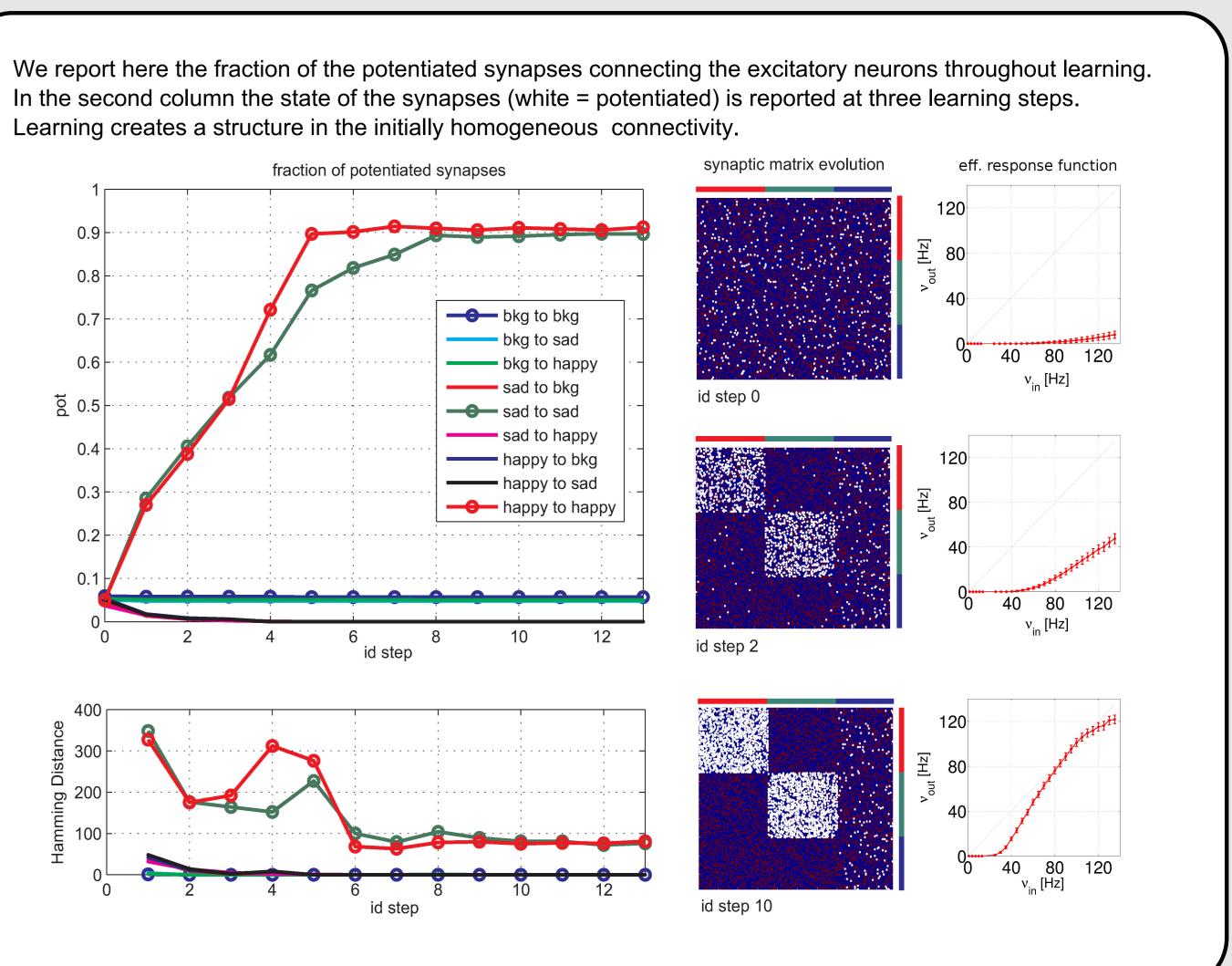
Learning is supported by on chip plastic Hebbian-like bistable synapses. The learning protocol consists in repeatedly presenting the visual cue stimuli. In

After presenting the stimulus few times there is an increase in the activity of the network that is due to synaptic potentiation. The mature network is able, after





From a microscopic point of view, subset of synapses upgrade their synaptic efficacy to their high level. This increases self excitation in a subset of





Upon presentation of degraded visual stimuli the network is able to retrieve the activity patterns corresponding to the complete stimuli thus expressing pattern completion capabilities (see t = 23s in the figure).

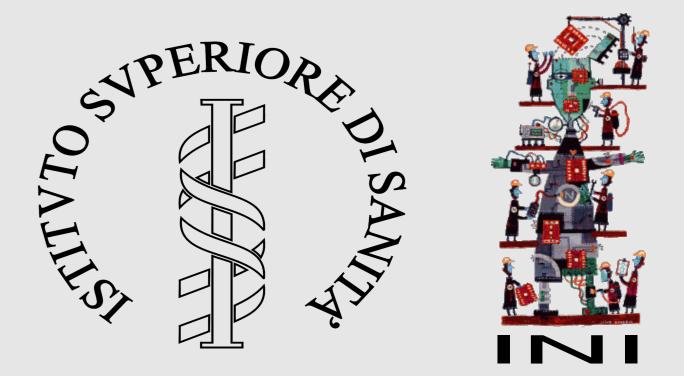


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References

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5 Synaptic matrix evolution

⁶ Robust associative memory

After learning we obtain a robust associative memory. When the network is in a memory state (attractor state), the ongoing dynamics makes it stable against distractors (see t = 16s in the figure)

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